## Adiabatic elimination for classical fermionic systems

This article has been downloaded from IOPscience. Please scroll down to see the full text article.
1987 J. Phys. A: Math. Gen. 204371
(http://iopscience.iop.org/0305-4470/20/13/037)
View the table of contents for this issue, or go to the journal homepage for more

Download details:
IP Address: 129.252.86.83
The article was downloaded on 31/05/2010 at 11:06

Please note that terms and conditions apply.

# Adiabatic elimination for classical fermionic systems 

Christian Elphick $\dagger$<br>Laboratoire de Physique Théorique $\ddagger$, Université de Nice, Parc Valrose, 06034 Nice Cedex, France

Received 31 October 1986


#### Abstract

We present the reduction to a normal form of a Grassmannian differential equation describing a classical fermionic system in the neighbourhood of an instability. As an application of the method presented we show that the anticommuting version of the normal form associated with (a) the Hopf bifurcation (a simple pair of imaginary eigenvalues) leads to the overdamped Grassmann harmonic oscillator, and (b) the resonant Hopf bifurcation 1:1 (a double pair of semisimple imaginary eigenvalues) corresponds exactly to the Thirring model for Grassmann solitons.


## 1. Introduction

A great deal of attention has been devoted recently to the study of Grassmann variables in connection with the description of Fermi systems (Berezin and Marinov 1977, Elphick 1986, Ohnuki and Kamefuchi 1980). This stems from the fact that Grassmann variables are the classical counterparts of fermionic quantum operators or, in other words, for each Fermi operator one can construct an eigenbasis of coherent states such that its eigenvalues belong to a Grassmann algebra. Therefore the classical version of the Heisenberg equations of motion for a Fermi system corresponds to an evolution equation whose phase space is a Grassmann algebra, i.e. a differential equation for anticommuting variables. Particular models involving this type of equation have been extensively studied by Berezin and Marinov (1977) in the context of supersymmetry, by Kulish and Nissimov (1976) who considered the anticommuting massive Thirring model (Амтм) and by Morris (1978) who determined a Bäcklund transformation for the amтm generalising the prolongation structure method of Wahlquist and Estabrook (1975) to Grassmann algebra-valued differential forms.

It is worthwhile pointing out that differential equations for Grassmann variables are also naturally encountered in the description via the path integral of a quantum mechanical Fermi system. In this description, if $H\left(a_{j}, a_{j}^{\dagger}, t\right)$ denotes the normal ordered Hamiltonian of the fermionic system then the integral kernel of the evolution operator $U\left(\theta_{(f)}, t_{f} ; \theta_{(i)}, t_{i}\right)\left(\theta_{(f)}, \theta_{(i)}\right.$ are Grassmann variables and ${ }^{*}$ is the analogue of $\left.\dagger\right)$ is given by a functional integral over a Grassmann algebra:

$$
\begin{array}{r}
U\left(\theta_{(f)}, t_{f} ; \theta_{(\mathrm{i})}, t_{i}\right)=\int \mathscr{D}\left(\theta_{j}^{*}, \theta_{j}\right) \exp \left[\frac{1}{2}\left(\theta_{(f) k}^{*} \theta_{(f) k}+\theta_{(i) k}^{*} \theta_{(i) k}\right)\right. \\
\left.+\mathrm{i} \int_{t_{i}}^{t_{h}} \mathrm{~d} t\left(\frac{1}{2 \mathrm{i}}\left(\theta_{k}^{*} \dot{\theta}_{k}-\dot{\theta}_{k}^{*} \theta_{k}\right)-h\left(\theta_{j}, \theta_{j}^{*}, t\right)\right)\right] \tag{1}
\end{array}
$$

† Address from 1 September 1987: Department of Astronomy, Columbia University, New York, NY 10027, USA.
$\ddagger$ Unité Associée au CNRS.
where $h$ is the 'classical value' of $H$ when we replace the operators $a_{j}^{\dagger}, a_{j}$ by the Grassmann variables $\theta_{j}^{*}, \theta_{j}$. Explicit calculation of the path integral leads to the evaluation of the classical action on the extremal trajectory satisfying the classical equations of motion:

$$
\begin{equation*}
\frac{1}{\mathrm{i}} \dot{\theta}_{j}=\frac{\partial h}{\partial \theta_{j}^{*}} \quad \frac{1}{\mathrm{i}} \dot{\theta}_{j}^{*}=\frac{\partial h}{\partial \theta_{j}} \tag{2}
\end{equation*}
$$

(since $\theta_{j}, \theta_{j}^{*}$ anticommute the sign in the Hamilton equations is the same). Therefore we have naturally arrived at a set of Grassmannian differential equations. (If a fermionic field theory is considered then (2) is a set of partial differential equations (PDE) for Grassmann fields (this type of equation has recently received much attention in connection with supersymmetric extensions of integrable models and superevaluation equations (Gürses and Oğuz 1985, Kupershmidt 1984, Olshanetsky 1983, Roy Chowdhury and Roy 1986)). For the sake of clarity we consider here only the case of a finite number of degrees of freedom, the generalisation to PDE for Grassmann fields being straightforward.)

We consider here, with no particular model in mind, a general non-linear Grassmann differential equation (not necessarily derived from a variational principle) describing a classical Fermi system undergoing a degenerate bifurcation. Such a situation is characterised by the linear instability of one or several Grassmann modes (critical modes) while the others remain strongly damped. We show that by an appropriate non-linear change of variables the original differential system can be reduced to a simpler one such that its asymptotic dynamics is described only by an equation for the critical modes referred to as the normal form equation.

The plan of this paper is as follows: in § 2 we present some preliminaries on Grassmann algebras and notation to be used in the other sections. Section 3 is devoted to developing the method leading to the normal form and the equation for the non-critical modes. In $\S 4$ we make a useful comment on adiabatic elimination for Grassmann variables and finally in § 5 we apply the techniques presented to some specific examples of low codimension (minimum number of parameters needed to unfold the critical situation) and, in particular, we study how the normal form corresponding to the double Hopf bifurcation (two pairs of semisimple imaginary eigenvalues) leads to the Thirring model.

## 2. Brief preliminary on Grassmann algebras

An algebra whose generators $\xi_{1}, \ldots, \xi_{n}$ satisfy the relations

$$
\begin{equation*}
\left[\xi_{i}, \xi_{j}\right]_{-}=\xi_{i} \xi_{j}+\xi_{j} \xi_{i}=0 \quad i, j=1, \ldots, n \tag{3}
\end{equation*}
$$

is called a Grassmann algebra $\mathscr{G}_{n}$ with $n$ generators. If an algebra $\mathscr{G}$ possesses an infinite countable number of generators satisfying (3) for any $i, j$ belonging to a countable set $I$ then we will refer to $\mathscr{G}$ as an infinite-dimensional Grassmann algebra. $\mathscr{G}_{n}$ is also a $2^{n}$-dimensional linear space which is the direct sum of linear spaces

$$
\begin{equation*}
\mathscr{G}_{n}=\oplus_{k} \mathscr{G}_{n}^{(k)} \tag{4}
\end{equation*}
$$

where $\mathscr{G}_{n}^{(k)}$ is $\binom{n}{k}$ dimensional and generated by monomials of degree $k\left\{\xi_{i_{1}} \xi_{i_{2}} \ldots \xi_{i_{k}}\right\}$. $\mathscr{G}_{n}^{(0)}$ is a one-dimensional linear space whose generator (the identity of $\mathscr{\mathscr { G }}_{n}$ ) can be regarded as the generator of $\mathbb{C}$.

It follows that an arbitrary element $g$ of $\mathscr{G}$ can be represented in the form of a linear combination of monomials
$g=\alpha_{0}+\sum_{i \in I} \alpha_{i} \xi_{i}+\sum_{i_{1}, i_{2} \in I} \alpha_{i_{1} i_{2}} \xi_{i_{1}} \xi_{i_{2}}+\ldots+\sum_{i_{1}, i_{2}, \ldots, i, \in I} \alpha_{i_{1} i_{2} \ldots, i_{1}} \xi_{1} \xi_{1} \xi_{2} \ldots \xi_{1}+\ldots$.
This decomposition is unique if all the coefficients $\alpha_{i_{1} i_{2} \ldots i_{i}} \in \mathbb{C}$ are totally antisymmetric in $i_{1}, \ldots, i_{j} \in I$. An element in $\mathscr{G}$ of the form

$$
\begin{equation*}
\sum_{i_{1}, i_{2}, \ldots, i_{k}} \alpha_{i_{1} i_{2}, \ldots i_{k}} \xi_{i_{1}} \xi_{i_{2}} \ldots \xi_{i_{k}} \tag{6}
\end{equation*}
$$

is called a homogeneous element of degree $k$. Therefore $\mathscr{G}$ can be decomposed as $\mathscr{G}_{\mathrm{e}} \oplus \mathscr{G}_{0}$ where $\mathscr{G}_{\mathrm{e}}$ (resp $\mathscr{G}_{0}$ ) is the set of elements in $\mathscr{G}$ which are linear combinations of homogeneous elements of even (resp odd) degree. Elements belonging to $\mathscr{G}_{\mathrm{e}}$ (resp $\mathscr{G}_{0}$ ) are called even (resp odd). It follows that for any $g$ in $\mathscr{G}, g \mathscr{G}_{\mathrm{e}}=\mathscr{G}_{\mathrm{e}} g$ and $g \mathscr{G}_{\mathrm{o}}=-\mathscr{G}_{\mathrm{o}} g$ (for $g$ odd).

If $\mathscr{G}$ is endowed with an inner product $\langle$,$\rangle then we can define a one-to-one$ mapping of $\mathscr{G}$ onto itself $g \rightarrow g^{*}$ such that (i) $\left(g^{*}\right)^{*}=g$, (ii) $\left(g_{1} g_{2}\right)^{*}=g_{2}^{*} g_{1}^{*}$, (iii) $(\alpha g)^{*}=\bar{\alpha} g^{*}, \alpha \in \mathbb{C}$, and (iv) $\langle f, g\rangle=\left\langle f^{*}, g^{*}\right\rangle$. This mapping is called the involution in $\mathscr{G}$ and the elements $g, g^{*}$ are called adjoint to each other.

Finally we review some basic properties of derivation and integration of Grassmann algebras. For the sake of clarity we will illustrate these concepts with the following simple example. We consider a two-level Fermi system with the two operators $a, a^{+}$ satisfying $a a^{\dagger}+a^{\dagger} a=1, a^{2}=\left(a^{\dagger}\right)^{2}=0$. We represent them acting on the fourdimensional Grassmann algebra generated by $\theta, \theta^{*}\left(\theta^{2}=\left(\theta^{*}\right)^{2}=0, \theta \theta^{*}+\theta^{*} \theta=0\right)$. An element $g$ in $\mathscr{G}_{2}$ has the form

$$
\begin{equation*}
g\left(\theta, \theta^{*}\right)=g_{0}+g_{1} \theta+g_{2} \theta^{*}+g_{3} \theta \theta^{*} \tag{7}
\end{equation*}
$$

We introduce in $\mathscr{G}_{2}$ the linear left derivation

$$
\begin{equation*}
\partial^{\prime} g / \partial \theta=g_{1}+g_{3} \theta^{*} \quad \partial^{\prime} g / \partial \theta^{*}=g_{2}-g_{3} \theta . \tag{8}
\end{equation*}
$$

Decomposing $\mathscr{G}_{2}$ as $\mathscr{G}_{2(\mathrm{e})} \oplus \mathscr{G}_{2(\mathrm{o})}$ we easily derive the following properties. Let $g$ be an arbitrary element in $\mathscr{G}_{2}$; then

$$
\begin{equation*}
\frac{\partial^{\prime}\left(g_{1} g\right)}{\partial \xi}=\left(\frac{\partial^{\prime} g_{1}}{\partial \xi}\right) g \pm g_{1} \frac{\partial^{\prime} g}{\partial \xi} \tag{9}
\end{equation*}
$$

where the $+\operatorname{sign}(r e s p-)$ holds if $g_{1} \in \mathscr{G}_{2(\mathrm{e})}$ (resp $\mathscr{G}_{2(\mathrm{o})}$ ) and $\xi$ stands for $\theta$ or $\theta^{*}$.
If $g, f \in \mathscr{G}_{2}$ then we define the scalar product by

$$
\begin{equation*}
\langle g, f\rangle=g_{0} \bar{f}_{0}+g_{1} \bar{f}_{1}+g_{2} \bar{f}_{2}+g_{3} \bar{f}_{3} \tag{10}
\end{equation*}
$$

(a bar stands for complex conjugate) which can be written as the Grassmann integral

$$
\begin{equation*}
\int \exp \left(-\left(\theta_{1}^{*} \theta_{1}+\theta_{2}^{*} \theta_{2}\right)\right) g\left(\theta_{1}, \theta_{2}\right) \bar{f}\left(\theta_{2}^{*}, \theta_{1}^{*}\right) \mathrm{d} \theta_{1}^{*} \mathrm{~d} \theta_{1} \mathrm{~d} \theta_{2}^{*} \mathrm{~d} \theta_{2} \tag{11}
\end{equation*}
$$

where the integral symbol is defined by linearity starting from the requirements (Berezin 1966)
$\int \mathrm{d} \theta=\int \mathrm{d} \theta^{*}=0 \quad \int \theta \mathrm{~d} \theta=\int \theta^{*} \mathrm{~d} \theta^{*}=1 \quad\left[\mathrm{~d} \theta, \mathrm{~d} \theta^{*}\right]_{-}=0$
and $\left(\theta, \theta^{*}\right)$ anticommute with ( $\mathrm{d} \theta, \mathrm{d} \theta^{*}$ ). From (8) and (12) we clearly see that the integral and the left derivation are identical.

The above properties are easily generalised to several degrees of freedom.

## 3. Reduction to the normal form and the equation for the stable modes

Let $\mathscr{G}$ be an infinite-dimensional complex Grassmann algebra with an involution. Let us consider in $\mathscr{G}$ a finite family $\mathscr{F}$ of $n$ real odd elements depending on a real parameter $t$ :

$$
\begin{equation*}
\mathscr{F}=\left\{\theta_{i}(t) \in \mathscr{G}_{0} ; \theta_{i}(t)=\theta_{i}^{*}(t),\left[\theta_{i}(t), \theta_{j}(t)\right]=0, \forall i, j=1, \ldots, n, \forall t \in\left[t_{0},+\infty\right)\right\} . \tag{13}
\end{equation*}
$$

An element $\theta_{i}$ in $\mathscr{F}$ can be represented as

$$
\begin{equation*}
\theta_{i}(t)=\sum_{j \in I} f_{i}^{j}(t) \xi_{j}+\sum_{j_{1} j_{2}, j_{3} \in I} f_{i}^{j_{1} j_{2} j_{3}}(t) \xi_{j_{1}} \xi_{j} \xi_{j_{3}}+\ldots \tag{14}
\end{equation*}
$$

where the coefficients $f_{i}^{j_{1} j_{2} \cdots j_{P}}(t)$ belong to $C^{\infty}\left(\left[t_{0}, \infty\right)\right)$.
We assume that elements in $\mathscr{F}$ describe a classical Fermi system and evolve with $t$ according to

$$
\begin{equation*}
\frac{\mathrm{d} \boldsymbol{\theta}}{\mathrm{~d} t}=L \boldsymbol{\theta}+\boldsymbol{N}(\boldsymbol{\theta}) \quad \boldsymbol{\theta}\left(t=t_{0}\right)=\boldsymbol{\theta}_{0} \tag{15}
\end{equation*}
$$

where $\boldsymbol{\theta}$ is a $n$-dimensional Grassmann vector, $\boldsymbol{\theta}=\theta_{i} \boldsymbol{e}^{i}$ (sum over repeated indices), $\boldsymbol{e}^{i}, i=1, \ldots, n$, being the canonical basis of a vectorial space $E, L$ is a real linear operator acting on $E$ and $\boldsymbol{N}(\boldsymbol{\theta})$ stands for an arbitrary odd non-linearity (note that $\mathrm{d} \theta / \mathrm{d} t$ is odd and if (15) is a Hamiltonian system, as in (2), then $h$ must belong to $\mathscr{G}_{\mathrm{e}}$ ). Note that if $n=2$ then (15) reduces to a linear equation. In the following, $n>2$ will be implicitly assumed. We also suppose that $L$ and $N$ depend on a parameter $\mu \in \mathbb{R}^{P}$ and that in (15) we are at a point $\mu_{c}$ such that $L$ has $n_{c}$ eigenvalues with a vanishing real part which we call critical, while the rest of the eigenvalues denoted by $\gamma_{\alpha}, \alpha=1, \ldots, M=n-n_{c}$, are different and have a strictly negative real part. In this scenario, assumed to persist in a small neighbourhood of $\mu_{c}$, the asymptotic solution of (15) $\theta=0$ is linearly unstable. Since $L$ is real, the critical eigenvalues can only be zero or pure imaginary, in which case they are complex conjugate ( $\mathrm{i} \omega_{k},-\mathrm{i} \omega_{k}$ ) $k=$ $1, \ldots, s$ (for simplicity we assume they are semisimple). Then $n_{\mathrm{c}}=l^{\prime}+2 s$ where $l^{\prime}$ is the algebraic multiplicity of the zero eigenvalue.

According to our assumptions we can split $E$ into the direct sum of $L$-invariant subspaces $E_{\mathrm{c}} \oplus E_{\mathrm{s}}$, where $E_{\mathrm{s}}$ is the stable subspace spanned by the vectors $\boldsymbol{\psi}_{\alpha}, L \boldsymbol{\psi}_{\alpha}=$ $\gamma_{\alpha} \psi_{\alpha}, \alpha=1, \ldots, M$, and $E_{\mathrm{c}}$ is spanned by the generalised eigenvectors $\phi_{i}, i=1, \ldots, n_{\mathrm{c}}$, such that

$$
\begin{equation*}
L \boldsymbol{\phi}_{i}=ل_{j i} \boldsymbol{\phi}_{j} \tag{16}
\end{equation*}
$$

where the Jordan matrix is given by

$$
J=\left[\begin{array}{lllllll}
\Omega_{1} & & & & & &  \tag{17}\\
& \Omega_{2} & & & & & \\
& & & & & & \\
& & \Omega_{q} & & & & \\
& & & 0 & & & \\
& & & & \Omega_{1} & & \\
& & & & & \ddots & \\
& & & & & & \Omega_{s}
\end{array}\right]
$$

where $J_{i}$ is a $n_{i} \times n_{i}$ matrix with zeros in the diagonal and ones in the upper diagonal, 0 is a $l \times l$ null matrix, $\Omega_{j}$ is the diagonal matrix corresponding to the pair ( $\mathrm{i} \omega_{j},-\mathrm{i} \omega_{j}$ ) and $\Sigma_{i=1}^{q} n_{i}+l=l^{\prime}$.

Let us consider now in $\mathscr{G}$ a new finite family of odd variables
$\left\{A_{1}, A_{2}, \ldots, A_{l^{\prime}}, A_{l^{\prime}+1}, A_{l^{\prime}+2}=A_{l^{\prime}+1}^{*}, \ldots, A_{n_{\mathrm{c}}-1}, A_{n_{\mathrm{c}}}=A_{n_{\mathrm{c}}-1}^{*} ; B_{\alpha}, \alpha=1, \ldots, M\right\}$
defined through the non-linear change of variables

$$
\begin{equation*}
\boldsymbol{\theta}(t)=\sum_{i=1}^{n_{c}} A_{i}(t) \boldsymbol{\phi}_{i}+\sum_{\alpha=1}^{M} B_{\alpha}(t) \boldsymbol{\psi}_{\alpha}+\sum_{j=1}^{(m-1) / 2} \boldsymbol{\theta}^{[2 j+1]}\left(A_{i}, B_{\alpha}\right) \tag{18}
\end{equation*}
$$

where $m=n$ (resp $m=n-1$ ) if $n$ is odd (resp even) and $\boldsymbol{\theta}^{[2 j+1]}$ is homogeneous of degree $2 j+1$ in the variables $\left\{A_{i}, B_{\alpha}\right\}$. We look for equations for $\left\{A_{i}, B_{\alpha}\right\}$ of the form
$\frac{\mathrm{d} A_{i}}{\mathrm{~d} t}=\exists_{i j} A_{j}+\sum_{j=1}^{(m-1) / 2} f_{i}^{[2 j+1]}\left(A_{k}, B_{\beta}\right) \equiv \rrbracket_{i j} A_{j}+F_{i} \quad i=1, \ldots, n_{\mathrm{c}}$
$\frac{\mathrm{d} B_{\alpha}}{\mathrm{d} t}=\gamma_{\alpha} B_{\alpha}+\sum_{j=1}^{(m-1) / 2} g_{\alpha}^{[2 j+1]}\left(A_{k}, B_{\beta}\right) \equiv \gamma_{\alpha} B_{\alpha}+G_{\alpha} \quad \alpha=1, \ldots, M$
where $f_{i}^{[2 j+1]}, i=1, \ldots, n_{\mathrm{c}}$, and $g_{\alpha}^{[2 j+1]}, \alpha=1, \ldots, M$ are homogenous of degree $2 j+1$ in $\left\{A_{k}, B_{\beta}\right\}$. The idea is to choose $\boldsymbol{\theta}^{[2 j+1]}, j=1, \ldots, \frac{1}{2}(m-1)$, such that $F_{i}, G_{\alpha}$ can be taken as simple as possible. As we will see below, $G_{\alpha}$ will turn out to be linear in $B_{\alpha}$, $F_{i}$ independent of $B_{\beta}, \beta=1, \ldots, M$, and such that $F=F_{i} \phi_{i}$ is equivariant under the one-parameter Lie group generated by $\downarrow^{+}$(Elphick et al 1986).

From (18) we have

$$
\begin{equation*}
\frac{\mathrm{d} \boldsymbol{\theta}}{\mathrm{~d} t}=\frac{\mathrm{d} A_{i}}{\mathrm{~d} t} \frac{\partial^{\prime} \boldsymbol{\theta}}{\partial A_{i}}+\frac{\mathrm{d} B_{\alpha}}{\mathrm{d} t} \frac{\partial^{\prime} \boldsymbol{\theta}}{\partial B_{\alpha}} \tag{20}
\end{equation*}
$$

where the subscript $l$ means that in differentiating with respect to the variable $A_{i}$ or $B_{\alpha}$ we must displace it to the left before dropping it. By substituting (18) into (15), using (20) and equations (19a) and (19b) we obtain the following hierarchy of equations ( $j=0$ leads to a trivial verification):

$$
\begin{align*}
\mathscr{L} \boldsymbol{\theta}^{[2 j+1]} & =(\mathscr{A}+\mathscr{B}-L) \boldsymbol{\theta}^{[2 j+1]} \\
& =\boldsymbol{I}^{[2 j+1]}-f_{i}^{[2 j+1]} \boldsymbol{\phi}_{i}-\boldsymbol{g}_{\alpha}^{[2 j+1]} \boldsymbol{\psi}_{\alpha} \equiv \boldsymbol{K}^{[2 j+1]} \quad j=1, \frac{1}{2}(m-1) \tag{21}
\end{align*}
$$

where

$$
\begin{equation*}
\mathscr{A}=J_{i j} A_{j} \partial^{l} / \partial A_{i} \quad \mathscr{B}=\gamma_{\alpha} B_{\alpha} \partial^{l} / \partial B_{\alpha} \tag{22}
\end{equation*}
$$

and
$\boldsymbol{I}^{[2 j+1]}=\boldsymbol{N}^{[2 j+1]}-\sum_{k=1}^{j-1}\left[\left(\frac{\mathrm{~d} A_{i}}{\mathrm{~d} t}\right)^{[2 k+1]} \frac{\partial^{l}}{\partial \boldsymbol{A}_{i}}+\left(\frac{\mathrm{d} B_{\alpha}}{\mathrm{d} t}\right)^{[2 k+1]} \frac{\partial^{l}}{\partial B_{\alpha}}\right] \boldsymbol{\theta}^{[2(j-k)+1]}$.
If $j=1$, the last term in (23) is absent. The operator $\mathscr{L}=\mathscr{A}+\mathscr{B}-L$ in (21) is called the homological operator associated to $L$ (Arnold 1977, Elphick et al 1986) and acts on the tensor product $\mathscr{H}=E \otimes \mathscr{H}_{1} \otimes \mathscr{H}_{2}$ where $\mathscr{H}_{1}\left(\right.$ resp $\left.\mathscr{H}_{2}\right)$ is the linear space generated by odd monomials in the variables $A_{i}$ (resp $B_{\alpha}$ ). We endow $\mathscr{H}$ with the inner product

$$
\begin{equation*}
\langle,\rangle_{\mathscr{H}}=\langle,\rangle_{E} \cdot\langle,\rangle_{\mathscr{H}_{1}} \cdot\langle,\rangle_{\mathscr{H}_{2}} \tag{24}
\end{equation*}
$$

where $\langle,\rangle_{E}$ is such that $\left\{\phi_{i}, \psi_{\alpha}\right\}$ form an orthonormal basis and $\langle,\rangle_{\mathscr{H}_{1}}$ is given by (an analogous expression holds for $\mathscr{H}_{2}$ )

$$
\begin{equation*}
\left\langle f_{1}, f_{2}\right\rangle_{\mathscr{H}_{1}}=\int \exp \left(-\sum_{i=1}^{n_{\mathrm{c}}} A_{i}^{*} A_{i}\right) f_{1}\left(A_{j}\right) f_{2}^{*}\left(A_{j}\right) \mathrm{d} A_{n_{\mathrm{c}}}^{*} \mathrm{~d} A_{n_{\mathrm{c}}} \ldots \mathrm{~d} A_{1}^{*} \mathrm{~d} A_{1} \quad \forall f_{1}, f_{2} \in \mathscr{H}_{1} . \tag{25}
\end{equation*}
$$

We note that the above expression is a multiple Grassmann integral defined in the sense of § 2 . It is worthwhile remarking that the scalar product introduced for $\mathscr{H}_{1}$ (resp $\mathscr{H}_{2}$ ) is such that the operators $A_{i}, \partial^{l} / \partial A_{i}$ (resp $B_{\alpha}, \partial^{i} / \partial B_{\alpha}$ ) are adjoint to each other and satisfy

$$
\begin{align*}
& \left(a_{i}^{+}=A_{i}, a_{i}=\partial^{\prime} / \partial A_{i}, b_{\alpha}^{+}=B_{\alpha}, b_{\alpha}=\partial^{\prime} / \partial B_{\alpha}\right) \\
& {\left[a_{i}^{\dagger}, a_{i}\right]_{-}=\delta_{i j} \quad\left[b_{\alpha}^{+}, b_{\beta}\right]_{-}=\delta_{\alpha \beta}} \tag{26}
\end{align*}
$$

i.e. they are fermionic creation and annihilation operators in the Fock space $\mathscr{H}_{1}$ (resp $\mathscr{H}_{2}$ ) or, equivalently, $a_{j}+a_{j}^{\dagger}, \mathrm{i}\left(a_{j}-a_{j}^{\dagger}\right)\left(\right.$ resp $\left.b_{\alpha}+b_{\alpha}^{+}, \mathrm{i}\left(b_{\alpha}-b_{\alpha}^{+}\right)\right)$generate the Clifford algebra $C_{2 n_{\mathrm{c}}}\left(\operatorname{resp} C_{2 M}\right)$.

Using the above properties of the inner product in $\mathscr{H}$, the adjoint of $\mathscr{L}$ becomes

$$
\begin{equation*}
\mathscr{L}^{+}=\bar{J}_{i j} A_{i} \partial^{l} / \partial A_{j}+\bar{\gamma}_{\alpha} B_{\alpha} \partial^{l} / \partial B_{\alpha}-L^{+} \quad L^{+}={ }^{t} \bar{L} \tag{27}
\end{equation*}
$$

Therefore the adjoint of $\mathscr{L}$ corresponds to the homological operator associated to $L^{+}$. Graphically, this means that the following diagram is commutative:


Having defined $\mathscr{L}^{+}$we now focus our attention on equation (21). Since ker $L$ is non-trivial it easily follows that $\mathscr{L}$ is a linear non-invertible operator in $\mathscr{H}$. Therefore (21) will not have solutions unless $\boldsymbol{K}^{[2 j+1]} \in \operatorname{ran} \mathscr{L}, j=1, \ldots, \frac{1}{2}(m-1)$, from which we deduce that the unknown functions $f_{i}^{[2 j+1]} \boldsymbol{\phi}_{i}+g^{[2 j+1]} \boldsymbol{\psi}_{\alpha}, j=1, \ldots, \frac{1}{2}(m-1)$, have to be taken in the complementary space ker $\mathscr{L}^{+}\left(\mathscr{H}=\right.$ ran $\mathscr{L} \oplus$ ker $\mathscr{L}^{+}$) modulo (if needed to simplify the form of $(19 a)$ and $(19 b)$ ) some judicious choice in ran $\mathscr{L}$. This solvability condition is nothing but the Fredholm alternative. Therefore we have to carry out the following programme: (a) determine the generators of ker $\mathscr{L}^{+}$and (b) impose the Fredholm alternative $\boldsymbol{K}^{[2 j+1]}$ orthogonal to ker $\mathscr{L}^{\dagger}$ to determine $f_{i}^{[2 j+1]}, \boldsymbol{g}_{\alpha}^{[2 j+1]}$.

Assuming the non-resonant condition of the set $\left\{\gamma_{1}, \ldots, \gamma_{M}, \gamma_{M+1}=\right.$ $\left.\mathrm{i} \omega_{1}, \ldots, \gamma_{M+2 s}=-\mathrm{i} \omega_{s}\right\}$

$$
\begin{equation*}
\gamma_{i} \neq \sum_{j \in J} \gamma_{j} \quad \forall i \in I=\{1, \ldots, M+2 s\}, \forall J \subseteq I \tag{29}
\end{equation*}
$$

we easily obtain that ker $\mathscr{L}^{+}$is generated by vectors in $\mathscr{H}$ of the form

$$
\begin{equation*}
B_{\alpha} Y\left(A_{j}\right) \psi_{\alpha} \quad(\text { no sum over } \alpha) \tag{30a}
\end{equation*}
$$

where $Y \in \operatorname{ker} \mathscr{A}^{\dagger}\left(Y\right.$ must be an even element in $\left.\mathscr{H}_{1}\right)$, and by vectors $\boldsymbol{X}$ in $\mathscr{H}$ such that

$$
\begin{equation*}
\left(\mathscr{A}^{+}-L^{+}\right) \boldsymbol{X}=0 . \tag{30b}
\end{equation*}
$$

From (30b) it follows that $\boldsymbol{X}$ is of the form

$$
\begin{equation*}
\sum_{i=1}^{n_{c}} X_{i}\left(A_{j}\right) \phi_{i} \tag{31}
\end{equation*}
$$

where $X_{i}\left(A_{j}\right), i=1, \ldots, n_{\mathrm{c}}$, are linear combinations of monomials of odd degree in $\mathscr{H}_{1}$.
We conclude that the functions $F_{i}$ in (19a) can be chosen independent of $\left\{B_{1}, \ldots, B_{M}\right\}$ and such that $F=F_{i} \phi_{i}$ satisfies the differential equation

$$
\begin{equation*}
\left(\overline{( }_{i j} A_{i} \partial^{l} / \partial A_{j}-ل^{+}\right) \boldsymbol{F}=0 \tag{32}
\end{equation*}
$$

which can be rewritten in the following equivalent form:

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} \eta}\left(\mathrm{e}^{-\mathrm{s}^{+} \eta} \boldsymbol{F}\left(\mathrm{e}^{\mathrm{s}^{+} \eta} \boldsymbol{A}\right)\right)=0 \quad \forall \boldsymbol{A}=\sum_{i=1}^{n_{\mathrm{c}}} A_{i} \boldsymbol{\phi}_{i} \in E_{\mathrm{c}} \tag{33}
\end{equation*}
$$

and therefore $F$ is equivariant under $\mathrm{e}^{{ }^{j} \eta}$ ( $\eta$ is a real parameter).
From (30a), (30b) and (31), and using $\left\langle\boldsymbol{\phi}_{i}, \psi_{\alpha}\right\rangle_{E}=0, \forall i, \alpha$, we deduce that the functions $G_{\alpha}$ in (19b) are linear in $B_{\alpha}$ :

$$
\begin{equation*}
G_{\alpha}=B_{\alpha} H_{\alpha}\left(A_{j}\right) \quad \alpha=1, \ldots, M \tag{34}
\end{equation*}
$$

where the functions $H_{\alpha}$ satisfy

$$
\begin{equation*}
\bar{J}_{i j} A_{i} \frac{\partial^{l}}{\partial A_{j}} H_{\alpha}=0 . \tag{35}
\end{equation*}
$$

Using (35) we obtain that $G_{\alpha}$ satisfies

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} \eta} \mathrm{e}^{-\bar{\gamma}_{\alpha} \eta}\left(\mathrm{e}^{\gamma_{\alpha} \eta} \boldsymbol{B}_{\alpha} H_{\alpha}\left(\mathrm{e}^{\mathrm{d}^{+} \eta} \boldsymbol{a}\right)\right)=0 \quad \forall \alpha=1, \ldots, M \tag{36}
\end{equation*}
$$

which implies that $\boldsymbol{G}=\sum_{\alpha=1}^{M} G_{\alpha} \boldsymbol{\psi}_{\alpha}$ verifies

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} \eta} \mathrm{e}^{-1^{\eta} \eta} G\left(\mathrm{e}^{L^{\dagger} \eta}\binom{\boldsymbol{A}}{\boldsymbol{B}}\right)=0 \quad \forall \boldsymbol{A} \in E_{\mathrm{c}}, \boldsymbol{B} \in E_{\mathrm{s}} \tag{37}
\end{equation*}
$$

where $\Lambda=\operatorname{diag}\left(\gamma_{\alpha}, \alpha=1, \ldots, M\right)$.
Therefore, we conclude that the normal form equations (normal form for the critical modes plus the equation for the stable modes) (19a) and (19b):

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t}\binom{\boldsymbol{A}}{\boldsymbol{B}}=L\binom{\boldsymbol{A}}{\boldsymbol{B}}+\binom{\boldsymbol{F}}{\boldsymbol{G}} \tag{38}
\end{equation*}
$$

are characterised by the equivariance property $\left(R_{\eta}=\mathrm{e}^{L^{+} \eta}\right)$ :

$$
\begin{equation*}
R_{\eta}^{-1}\binom{\boldsymbol{F}\left(R_{\eta} \boldsymbol{C}\right)}{\boldsymbol{G}\left(R_{\eta} \boldsymbol{C}\right)}=\binom{\boldsymbol{F}(\boldsymbol{C})}{\boldsymbol{G}(\boldsymbol{C})} \quad \forall \boldsymbol{C}=\binom{\boldsymbol{A}}{\boldsymbol{B}} \in E \tag{39}
\end{equation*}
$$

which follows directly from (33) and (37), and leads to the simplest form for $F$ and G. We note that although we have used (29) to derive (39) a much more involved calculation also leads to (39) even in the case where (29) does not hold and $L$ admits eigenvalues with a positive real part.

It is worth remarking that (39) is a global characterisation for the normal form (38) giving a priori the simplest functional form for the non-linearities in (38). To know explicitly the coefficients of each admissible monomial (odd) we have to use the Fredholm alternative in (21).

We finally mention that in order to consider the unfolded situation in (15), i.e. when $\mu=\mu_{\mathrm{c}}+\delta \mu$, it suffices to replace the critical part of $L$ in (38) by the corresponding Arnold-Jordan matrix (Arnold 1971, Elphick et al 1986).

## 4. Remarks

It is worthwhile noting that since the functions $G_{\alpha}, \alpha=1, \ldots, M$ in (38) are linear in $B_{\alpha}$ and $\boldsymbol{F}$ only depends on the critical variables $A_{i}, i=1, \ldots, n_{c}$, then the Grassmann manifold $B$ defined by

$$
\begin{equation*}
B_{\alpha}=0 \quad \alpha=1, \ldots, M \tag{40}
\end{equation*}
$$

is invariant under the dynamics defined by (38). Therefore for any initial condition belonging to $B$ the system will remain on $B$ forever and its dynamics will be solely described in terms of the critical variables (equation (19a)).

Equivalently we can say that for times $t \gg \sup _{\alpha}|\operatorname{Re} \gamma \alpha|^{-1}$ all the variables $B_{\alpha}$ will relax to zero and therefore the subsequent asymptotic dynamics will be described by the slow variables $A_{i}$ through (19a). By replacing in (18) $B_{\alpha}=0, \alpha=1, \ldots, M$, and expressing the $M$ variables $\hat{\theta}_{\alpha}=\left\langle\boldsymbol{\theta}, \boldsymbol{\psi}_{\alpha}\right\rangle_{E}$ as functions of the $n_{c}$ variables $\tilde{\theta}_{j}=\left\langle\boldsymbol{\theta}, \boldsymbol{\phi}_{j}\right\rangle_{E}$ we arrive at the $M$ equations:

$$
\begin{align*}
& \hat{\theta}_{1}=\hat{\theta}_{1}\left(\tilde{\theta}_{1}, \ldots, \tilde{\theta}_{n_{c}}\right) \\
& \vdots  \tag{41}\\
& \vdots \\
& \hat{\theta}_{M}=\hat{\theta}_{M}\left(\tilde{\theta}_{1}, \ldots, \tilde{\theta}_{n c}\right)
\end{align*}
$$

which describe the Grassmann version of the stable manifold (Elphick et al 1986), Guckenheimer and Holmes 1983), and can be interpreted by saying that asymptotically the rapid variables $\hat{\theta}_{\alpha}$ follow the dynamics of the slow variables $\tilde{\theta}_{j}$.

The above description is just the Grassmann version of the adiabatic elimination method for differential equations with commuting variables (Haken 1977).

Once the non-linear change of variables (18) and equations (19a) and (19b) have been completely determined, appropriate initial conditions $A_{i}\left(t_{0}\right), B_{\alpha}\left(t_{0}\right)$ have to be added to (19a) and (19b) such that $\boldsymbol{\theta}\left(t_{0}\right)=\boldsymbol{\theta}_{0}$ through (18). A subsequent integration of (19a) and (19b) and replacement of its solutions $A_{i}\left(t, t_{0}\right), B_{\alpha}\left(t, t_{0}\right)$ in (18) leads to the solution of the original problem (equation (15)). As we will see in $\S 5$, there are a number of cases in which equations (19a) and (19b) can be easily integrated (Elphick (1986) considered in detail the case $J=\operatorname{diag}(0, \mathrm{i} \omega,-\mathrm{i} \omega)$ ) and therefore the method presented in $\S 3$ can be regarded as an integration technique of equations of the type (15).

## 5. Some examples

We introduce the notation $z^{n_{1}} z^{n_{2}} \ldots z^{n_{q}} l z \omega_{1} \ldots \omega_{s}$ (if, for example, $\omega_{1}=\omega_{2}=\omega$ we use the notation $2 \omega$ (resp $\omega^{2}$ ) for the semisimple (resp non-semisimple) case) to refer to the critical situation characterised by the matrix $\rrbracket$ given in (17).

### 5.1. No critical situation

Since there are no critical modes the original system is equivalent through (18) to the linear system

$$
\begin{equation*}
\mathrm{d} B_{\alpha} / \mathrm{d} t=\gamma_{\alpha} B_{\alpha} \quad \alpha=1, \ldots, M \tag{42}
\end{equation*}
$$

## 5.2. $z$ instability

$\rrbracket$ is the $1 \times 1$ null matrix and its associated Arnold-Jordan matrix is $(\mu)$. Since there is only one critical mode we easily obtain the normal form for $A_{1}$ (in the unfolded situation)

$$
\begin{equation*}
\mathrm{d} A_{1} / \mathrm{d} t=\mu A_{1} \tag{43}
\end{equation*}
$$

and the equation for the stable modes is the same as in (42).

## 5.3. $\omega$ instability (Hopf bifurcation)

Since now we have two critical modes, we cannot form with them a monomial of odd degree. Therefore, the normal form is (with an unfolding parameter)

$$
\begin{align*}
& \mathrm{d} A / \mathrm{d} t=(\mu+\mathrm{i} \omega) A  \tag{44a}\\
& \mathrm{~d} A^{*} / \mathrm{d} t=(\mu-\mathrm{i} \omega) A^{*} . \tag{44b}
\end{align*}
$$

From (35) we obtain the equation

$$
\begin{equation*}
\mathrm{i} \omega\left(A \frac{\partial^{l}}{\partial A}-A^{*} \frac{\partial^{l}}{\partial A^{*}}\right) H_{\alpha}=0 \tag{45}
\end{equation*}
$$

with solution $H_{\alpha}=k_{\alpha} A A^{*}$. Therefore the equations for the $B_{\alpha}, \alpha=1, \ldots, M$, are

$$
\begin{equation*}
\mathrm{d} B_{\alpha} / \mathrm{d} t=B_{\alpha}\left(\gamma_{\alpha}+k_{\alpha} A A^{*}\right) \tag{46}
\end{equation*}
$$

For $\mu=0$ equations (44a) and (44b) represent an overdamped complex Grassmann harmonic oscillator. We recall that for commuting variables the Hopf normal form represents a strictly non-linear oscillator.

## 5.4. $z^{3}$ instability

From (32) and (35) we obtain

$$
\begin{array}{ll}
\mathscr{A}^{\dagger} F_{1}=0 & \mathscr{A}^{\dagger} F_{2}=F_{1} \\
A^{\dagger} F_{3}=F_{2} & \mathscr{A}^{\dagger} H_{\alpha}=0 \tag{47}
\end{array}
$$

where

$$
\mathscr{A}^{+}=A_{1} \partial^{l} / \partial A_{2}+A_{2} \partial^{l} / \partial A_{3} .
$$

Since there are only three critical modes, the solutions of (47) are given by $F_{1}=F_{2}=F_{3}=0$ and $H_{\alpha}=k_{\alpha} A_{1} A_{2}$. Therefore (38) is (in the unfolded case)

$$
\begin{align*}
& \frac{\mathrm{d}^{3} A_{1}}{\mathrm{~d} t^{3}}+\mu_{1} \frac{\mathrm{~d}^{2} A_{1}}{\mathrm{~d} t^{2}}+\mu_{2} \frac{\mathrm{~d} A_{1}}{\mathrm{~d} t}+\mu_{3} A_{1}=0  \tag{48a}\\
& \frac{\mathrm{~d} B_{\alpha}}{\mathrm{d} t}=B_{\alpha}\left(\gamma_{\alpha}+k_{\alpha} A_{1} \frac{\mathrm{~d} A_{1}}{\mathrm{~d} t}\right) \quad \alpha=1, \ldots, M \tag{48b}
\end{align*}
$$

## 5.5. $z^{4}$ instability

In this case (32) and (35) give

$$
\begin{array}{ll}
\mathscr{A}^{\dagger} F_{1}=0 & \mathscr{A}^{\dagger} F_{2}=F_{1} \\
\mathscr{A}^{+} F_{3}=F_{2} & \mathscr{A}^{+} F_{4}=F_{3}  \tag{49}\\
\mathscr{A}^{+} H_{\alpha}=0 &
\end{array}
$$

where

$$
\mathscr{A ^ { + }}=A_{1} \frac{\partial^{l}}{\partial A_{2}}+A_{2} \frac{\partial^{l}}{\partial A_{3}}+A_{3} \frac{\partial^{l}}{\partial A_{4}} .
$$

Using the fact that the most general non-linear odd element in $\left(A_{1}, A_{2}, A_{3}, A_{4}\right)$ is of the form

$$
\begin{equation*}
\alpha_{1} A_{1} A_{2} A_{3}+\alpha_{2} A_{1} A_{2} A_{4}+\alpha_{3} A_{1} A_{3} A_{4}+\alpha_{4} A_{2} A_{3} A_{4} \tag{50}
\end{equation*}
$$

we readily obtain

$$
\begin{align*}
& F_{1}=\alpha A_{1} A_{2} A_{3} \\
& F_{2}=\alpha A_{1} A_{2} A_{4}  \tag{51}\\
& F_{3}=\alpha A_{1} A_{3} A_{4} \\
& F_{4}=\alpha A_{2} A_{3} A_{4} .
\end{align*}
$$

Similarly, by writing the most general even element as a linear combination of even monomials in ( $A_{1}, A_{2}, A_{3}, A_{4}$ ) and replacing it in the last equation of (49) we obtain as solutions

$$
H_{\alpha}=\left\{\begin{array}{l}
k_{\alpha} A_{1} A_{2}  \tag{52}\\
k_{\alpha}^{\prime} A_{1} A_{2} A_{3} A_{4} .
\end{array}\right.
$$

Finally the normal form can be further simplified by adding to (51) the following element in $\operatorname{ran}(\mathscr{A}-\sqrt[J]{ })$ :

$$
\begin{align*}
& F_{1}^{\prime}=-\alpha A_{1} A_{2} A_{3} \\
& F_{2}^{\prime}=-\alpha A_{1} A_{2} A_{3}  \tag{53}\\
& F_{3}^{\prime}=-\alpha A_{1} A_{3} A_{4} \\
& F_{4}^{\prime}=3 \alpha A_{2} A_{3} A_{4} .
\end{align*}
$$

The definitive equations are (with unfolding parameters $\mu_{1}, \mu_{2}, \mu_{3}, \mu_{4}$ )
$\frac{\mathrm{d}^{4} A_{1}}{\mathrm{~d} t^{4}}+\mu_{1} \frac{\mathrm{~d}^{3} A_{1}}{\mathrm{~d} \mathrm{t}^{3}}+\mu_{2} \frac{\mathrm{~d}^{2} A_{1}}{\mathrm{~d} t^{2}}+\mu_{3} \frac{\mathrm{~d} A_{1}}{\mathrm{~d} t}+\mu_{4} A_{1}=\nu \frac{\mathrm{d} A_{1}}{\mathrm{~d} t} \frac{\mathrm{~d}^{2} A_{1}}{\mathrm{~d} t^{2}} \frac{\mathrm{~d}^{3} A_{1}}{\mathrm{~d} t^{3}}$
$\frac{\mathrm{d} B_{\alpha}}{\mathrm{d} t}=B_{\alpha}\left(\gamma_{\alpha}+\eta_{\alpha} A_{1} \frac{\mathrm{~d} A_{1}}{\mathrm{~d} t}+\rho_{\alpha} A_{1} \frac{\mathrm{~d} A_{1}}{\mathrm{~d} t} \frac{\mathrm{~d}^{2} A_{1}}{\mathrm{~d} t^{2}} \frac{\mathrm{~d}^{3} A_{1}}{\mathrm{~d} t^{3}} \frac{\mathrm{~d}^{4} A_{1}}{\mathrm{~d} t^{4}}\right) \quad \alpha=1, \ldots, M$.

## 5.6. $2 \omega$ instability

We now have four critical anticommuting variables $\boldsymbol{A}_{1}, \boldsymbol{A}_{1}^{*}, \boldsymbol{A}_{2}, \boldsymbol{A}_{2}^{*}$. The Jordan matrix $\checkmark$ is given by

$$
\mathbb{\Omega}=\left(\begin{array}{cccc}
\mathrm{i} \omega & 0 & 0 & 0  \tag{55}\\
0 & -\mathrm{i} \omega & 0 & 0 \\
0 & 0 & \mathrm{i} \omega & 0 \\
0 & 0 & 0 & -\mathrm{i} \omega
\end{array}\right)
$$

and consequently $\mathrm{e}^{\mathrm{J}^{+} \eta}$ generates two independent rotations by $\omega \eta$ in the planes $\left(A_{1}, A_{1}^{*}\right)$ and ( $\boldsymbol{A}_{2}, \boldsymbol{A}_{2}^{*}$ ). Therefore using the invariance properties of $\S 3$ we conclude that the functions $G_{\alpha}$ are linear combinations of monomials of even degree invariant under the above rotations and under the permutation $A_{1} \rightarrow A_{2}$ :

$$
\begin{equation*}
G_{\alpha}=\delta_{\alpha}\left(A_{2}^{*} A_{2}+A_{1}^{*} A_{1}\right)+\beta_{\alpha}\left(A_{1}^{*} A_{1} A_{2}^{*} A_{2}\right) \quad \alpha=1, \ldots, M . \tag{56}
\end{equation*}
$$

The equivariance corresponding to $F=\left(F_{1}, F_{1}^{*}, F_{2}, F_{1}^{*}\right)$ in (39) leads to
$\mathrm{e}^{\mathrm{j} \omega \eta} F_{1}\left(\mathrm{e}^{-\mathrm{i} \omega \eta} A_{1}, \mathrm{e}^{\mathrm{j} \omega \eta} A_{1}^{*}, \mathrm{e}^{-\mathrm{i} \omega \eta} \boldsymbol{A}_{2}, \mathrm{e}^{\mathrm{i} \omega \eta} A_{2}^{*}\right)=F_{1}\left(\boldsymbol{A}_{1}, A_{1}^{*}, \boldsymbol{A}_{2}, \boldsymbol{A}_{2}^{*}\right)$
$\mathrm{e}^{-\mathrm{i} \omega \eta} F_{1}^{*}\left(\mathrm{e}^{-\mathrm{i} \omega \eta} \boldsymbol{A}_{1}, \mathrm{e}^{\mathrm{i} \omega \eta} \boldsymbol{A}_{1}^{*}, \mathrm{e}^{-\mathrm{i} \omega \eta} \boldsymbol{A}_{2}, \mathrm{e}^{\mathrm{i} \omega \eta} A_{2}^{*}\right)=F_{1}^{*}\left(\boldsymbol{A}_{1}, \boldsymbol{A}_{1}^{*}, \boldsymbol{A}_{2}, \boldsymbol{A}_{2}^{*}\right)$
and similar expressions for $F_{2}, F_{2}^{*}$.
From ( $57 a$ ) and ( $57 b$ ) we easily obtain that the most general odd elements satisfying the equivariance property are given by

$$
\begin{align*}
& F_{1}=\mathrm{i}\left(g_{1} A_{2}^{*} A_{2} A_{1}+g_{2} A_{1}^{*} A_{2} A_{1}\right)  \tag{58a}\\
& F_{2}=\mathrm{i}\left(g_{1} A_{1}^{*} A_{1} A_{2}+g_{2} A_{2}^{*} A_{1} A_{2}\right) \tag{58b}
\end{align*}
$$

where $g_{1}, g_{2}$ are constants.
From (56), (58a) and (58b) we arrive at the following equations for $\left(A_{1}, A_{1}^{*}, A_{2}^{*}, A_{2}^{*}, B_{\alpha}, \alpha=1, \ldots, M\right)$ :

$$
\begin{align*}
& \frac{1}{\mathrm{i}} \frac{\mathrm{~d} A_{1}}{\mathrm{~d} t}=\omega A_{1}+\left(g_{1} A_{2}^{*}+g_{2} A_{1}^{*}\right) A_{2} A_{1}  \tag{59a}\\
& \frac{1}{\mathrm{i}} \frac{\mathrm{~d} A_{2}}{\mathrm{~d} t}=\omega A_{2}+\left(g_{1} A_{1}^{*}+g_{2} A_{2}^{*}\right) A_{1} A_{2}  \tag{59b}\\
& \frac{\mathrm{~d} B_{\alpha}}{\mathrm{d} t}=B_{\alpha}\left(\gamma_{\alpha}+\delta_{\alpha}\left(A_{1}^{*} A_{1}+A_{2}^{*} A_{2}\right)+\beta_{\alpha} A_{1}^{*} A_{1} A_{2}^{*} A_{2}\right) . \tag{60}
\end{align*}
$$

The equations for $A_{1}^{*}, A_{2}^{*}$ are obtained from (59a) and (59b) by taking the involution.
Let us suppose now that the system considered is invariant under the independent reflections $A_{1} \rightarrow-A_{1}, A_{2} \rightarrow-A_{2}$. This implies $g_{2}=0$. By choosing $g_{1}$ real and defining the new variables

$$
\begin{array}{ll}
\phi_{1}=A_{1}+\mathrm{i} A_{2}^{*} & \phi_{1}^{*}=A_{1}^{*}-\mathrm{i} A_{2}  \tag{61}\\
\phi_{2}=A_{1}-\mathrm{i} A_{2}^{*} & \phi_{2}^{*}=A_{1}^{*}+\mathrm{i} A_{2}
\end{array}
$$

equations (59a) and (59b) can be equivalently written as

$$
\begin{align*}
& \frac{1}{\mathrm{i}} \frac{\mathrm{~d} \phi_{1}}{\mathrm{~d} t}=\omega \phi_{2}+\frac{1}{2} g_{1} \phi_{2}^{*} \phi_{2} \phi_{1}  \tag{62a}\\
& \frac{1}{\mathrm{i}} \frac{\mathrm{~d} \phi_{2}}{\mathrm{~d} t}=\omega \phi_{1}+\frac{1}{2} g_{1} \phi_{1}^{*} \phi_{1} \phi_{2} \tag{62b}
\end{align*}
$$

which is nothing but the anticommuting Thirring model describing Grassmann solitons if we identify $\omega$ with a mass $m$ and $t$ with the variable $\xi=\lambda x-\lambda^{-1} t, \lambda \in \mathbb{R}$, defined in a system moving with the soliton with a velocity $\lambda^{-1}$ in the laboratory frame (Morris 1978).

## References

Arnold V I 1971 Russian Math. Surveys 2629

- 1977 Geometrical Methods in the Theory of Ordinary Differential Equations (Berlin: Springer)

Berezin F A 1966 The Method of Second Quantisation (New York: Academic)
Berezin F A and Marinov N S 1977 Ann. Phys., NY 104336
Elphick C 1987 J. Math. Phys. 28 to be published

Elphick C, Tirapegui E, Coullet P, Brachet M E and looss G 1986 Physica D submitted
Guckenheimer J and Holmes P 1983 Nonlinear Oscillations, Dynamical Systems and Bifurcations of Vector Fields (Berlin: Springer)
Gürses M and Oǵuz Ö 1985 Phys. Lett. 108A 437
Haken H 1977 Synergetics-An Introduction (Berlin: Springer)
Kulish D and Nissimov E 1976 JETP Lett. 24247
Kupershmidt B A 1984 Phys. Lett. 102A 213
Morris H C 1978 J. Math. Phys. 1985
Ohnuki Y and Kamefuchi S 1980 J. Math. Phys. 21601
Olshanetsky M A 1983 Commun. Math. Phys. 8863
Roy Chowdhury A and Roy S 1986 J. Math. Phys. 272464
Wahlquist H D and Estabrook F G 1975 J. Math. Phys. 161

